Compressed sensing accelerated broadband 3D phase encoded turbo spin-echo imaging for geometrically undistorted imaging in the presence of field inhomogeneities

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Purpose: To obtain geometrically undistorted MR images in the presence of off-resonance effects in an acceptable time frame

Introduction: Field inhomogeneities have detrimental effects in conventional magnetic resonance imaging (MRI) and can degrade the image quality by geometrical distortions, signal misregistration, signal dephasing and incomplete excitation. Off-resonance effects originating from magnetic susceptibility differences within the subject (e.g. interventional devices, orthopedic implants, contrast agents) constitute a serious obstacle when accurate spatial localization is required. In this study, we explore the potential of purely 3D phase encoded spin-echo (3D-PE-SE) sequences to produce geometrically undistorted images in a clinically acceptable timeframe. To achieve this goal a 3D-PE-SE is accelerated by combining turbo acceleration³ and compressed sensing⁴ by implementing a 3D-PE-TSE sequence with broadband rf pulses and dedicated undersampling patterns.

Methods: Objects: A grid phantom containing a titanium implant ($\Delta \chi$ =182ppm) and a healthy volunteer with titanium screws in the knee were scanned to investigate the performance of the CS 3D-PE-TSE sequence.

Pulse sequences: A multi-spectral 3D-SE (ms3D-SE)², 3D-PE-SE and 3D-PE-TSE sequence were implemented on a 1.5T MR system (Philips, Best, The Netherlands). For the 3D-PE-TSE scan the flip angle of the first refocusing pulse was increased to $((180+\alpha)/2)$, where α is the desired refocusing flip angle, to reduce oscillations in the signal amplitude over the echo train⁵. For standard block pulses and a $B_{1,max}$ of $23\mu T$ a bandwidth up to 3.5 kHz could be achieved. The acquisition parameters are indicated in table 1. The 2D-TSE, 3D-(ms)SE and CT images act as references.

Sampling pattern design: A 3D spherical sampling pattern with a stepwise T₂ weighting was obtained by sorting the k-space coordinates in spherical layers each corresponding to a certain echo number and consisting of an equal number of points (fig 1). All sampling points in a certain layer are therefore sampled at the same 'echo time' and have an equal T2 weighting. Variable density undersampling patterns for CS-TSE accelerated imaging were designed in a similar fashion.

CS reconstruction: A non-linear conjugate gradient solver⁴ was used to minimize

 $\lambda_{w} | | \psi_{w} m | |_{1} + \lambda_{TV} TV(m)$, where $| | \psi_{w} m | |_{1}$ is the L₁ norm regularization in the wavelet transform domain and TV(m) a total variation regularization in the image domain with weighting factors λ_w and λ_{TV} . The original 2D regularizations were replaced with a 3D wavelet (Daubechies 6) L₁ norm regularization (λ_w) and a 3D total variation norm regularization (λ_{TV}) to reconstruct the 3D-PE-(T)SE data with three undersampled dimensions.

Results: The spatial encoding of 3D-PE-(T)SE was unaffected by susceptibility induced off-resonance effects (fig 2d,3), which did cause geometrical distortions and/or signal hyper-intensities in broadband 3D-SE (fig 2a) and, to a lesser extent, in ms3D-SE (fig 2b,c). The CS-TSE combination resulted in an overall acceleration factor of 60 (fig 3), decreasing the original 3D-PE-SE scan time from 7 hours (fig 3a) to 7

minutes (fig 3d) at the cost of some blurring, CS accelerated 3D-PE-TSE in vivo images of a titanium screw acquired in 20 (fig 4d) and 10 minutes (fig 4e) produced geometrically undistorted images unlike conventional 3D-TSE (fig 4b-c).

Discussion: This work demonstrates the feasibility to obtain geometrically accurate images near severe field inhomogeneities in acceptable timeframes. The current method may be applied in fields that require high spatial fidelity such as orthopedic imaging, hybrid MR imaging methods and radiotherapy.

References: 1. C.J.G. Bakker, Magn. Reson. Imaging 31 p86-95 (2013), 2. K.M. Koch, Magn. Reson. Med. 61 p381-390 (2009), 3. N.S. Artz, Magn. Reson. Med. 71 p681-690 (2013), M. Lustig, Magn. Reson. Med. 58, p1182-1195 (2007), 5. Alsop, Mag. Reson. Med. 37 p176-184

		Voxel	BWgr	BWrf	Time	Accel.
Scan	Fig	(mm)	(Hz/pix)	(kHz)	(min)	factor
SE	2a	2x1.5x5	505	5.0	3.5	
msSE	2b	2x1.5x5	505	1.7	17.5	
msSE	2c	2x1.5x5	1011	1.7	17.5	
PE-SE	2d,3a	2x1.5x5		5.0	436	0
PE-SE	3b	2x1.5x5		5.0	73	6
PE-TSE	3c	2x1.5x5		2.9	21.8	20
PE-TSE	3d	2x1.5x5		2.9	7.3	60
TSE	4b	1.3x1x1.3	218	2.9	3.5	
TSE	4c	1.3x1x1.3	218	2.9	3.5	
PE-TSE	4d	1.3x1x1.3		2.9	19.8	60
PE-TSE	4e	1.3x1x2.5		2.9	9.8	60

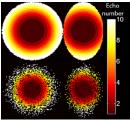


Fig 1: Sampling patterns for 3D-PE-TSE data with a spherical shutter (top row) and CS acceleration (bottom row). The kx-ky (left) and ky-kz plane (right) through the center of kspace are shown for an acquisition matrix of 96x96x64, which was used to acquire fig 4.

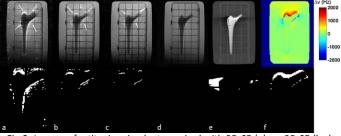
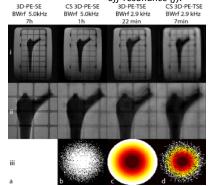


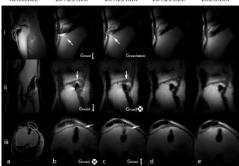
Fig 2: Images of a titanium implant acquired with 3D-SE (a), ms3D-SE (b,c), 3D-PE-SE (d) and CT (e) plus a field offset map (f). The bottom row highlights hyper- (a-d) or hypointense (e) voxels and regions with $\Delta v > 1 kHz$ off-resonance (f).
3D-PE-TSE CS 3D-PE-TSE

3D-TSE

2D-TSE



sampling pattern in kz=0 (iii) are shown.



3D-TSE

CS 3D-PE-TSE CS 3D-PE-TSE

Fig 3: Fully sampled (a,c) and CS (b,d) images Fig 4: In vivo mages of a titanium screw in the knee of a titanium implant (i,ii) acquired with 3D- acquired with 2D-TSE(a), 3D-TSE (b,c), 3D-PE-TSE PE-SE (a,b) or 3D-PE-TSE (c,d) and the (d,e) reformatted in three orientations (i-iii). The micro coil is indicated in (a,i) and (a,iii).

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