## A Theory for Sampling in k-Space - Parallel Imaging as Approximation in a Reproducing Kernel Hilbert Space

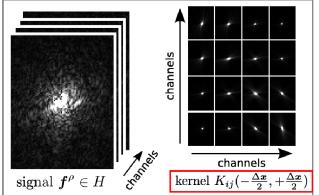
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## Target Audience: Image reconstruction researchers

**Introduction:** We show that parallel imaging can be formulated as an approximation of vector-valued functions in a Reproducing Kernel Hilbert Space (RKHS). This formulation provides both a theoretical foundation for reconstruction and sampling in k-space as well as new k-space metrics for interpolation error and noise amplification which go beyond the traditional image-domain g-factor metric.

**Theory:** All possible multi-channel signals in parallel imaging span only a small subspace of a k-space. It can be shown that this subspace is a RKHS with a matrix-valued kernel derived from the coil sensitivities (Fig. 1).<sup>2</sup> As illustrated in Figure 2, interpolation in k-space from arbitrary, Cartesian or non-Cartesian, samples can then be formulated in the framework of approximation theory.<sup>3</sup> Interpolation weights (cardinal functions), bounds for the interpolation error (power function), and noise amplification (Frobenius norm) can be computed locally for all k-space positions.



encoding functions signal equation  $K_{ij}(\boldsymbol{x}, \boldsymbol{y}) = \langle \epsilon^{\boldsymbol{x}, i}, \epsilon^{\boldsymbol{y}, j} \rangle_{L^2}$  $\epsilon^{\boldsymbol{x},j}(\boldsymbol{r}) = e^{2\pi\sqrt{-1}\boldsymbol{x}\cdot\boldsymbol{r}}\overline{c_{j}(\boldsymbol{r})}$  $f_i^{\rho}(\boldsymbol{x}) = \langle \epsilon^{\boldsymbol{x},i}, \rho \rangle_{L^2}$ sampling (reproduction) equation signal  $f^{\rho} \in H \subset D$ image  $\rho \in I$  $f_i^{
ho}(oldsymbol{x}_k) = \langle K_{\cdot i}(\cdot, oldsymbol{x}_k), oldsymbol{f}^{
ho} 
angle_H$  $F:I \to \widetilde{D}$  $D = C^{\infty}(\mathbb{R}^2, \mathbb{C}^N)$  $I = L^2(\Omega, \mathbb{C})$ sampling interpolation in k-space  $T:D \to Y$  $\hat{f}(\boldsymbol{x}) = \sum_{ki} y_{ki} \boldsymbol{u}^{k.i}(\boldsymbol{x})$  $f^{\rho} \mapsto y$ samples  $y \in Y$ cardinal functions, solution of:  $y_{ki} = f_i^{\rho}(\boldsymbol{x}_k)$  $\sum_{k,i} K_{ij}(\boldsymbol{x}_k, \boldsymbol{x}_l) u_n^{k,i}(\boldsymbol{x}) = K_{nj}(\boldsymbol{x}, \boldsymbol{x}_l)$ 

**Figure 1:** The multi-channel k-space is a Reproducing Kernel Hilbert Space (RKHS) with a matrix-valued kernel. This kernel uniquely characterizes the space.

**Figure 2 (color):** The mathematical relationship between the space of images I, continuous multi-channel k-space signals H (with sensitivities  $c_i$ ), and discrete samples Y in parallel imaging. Sampling and reconstruction in k-space can be formulated using a RKHS with kernel K.

**Methods:** Fully-sampled 8-channel data of a human brain (IR-FLASH, TR/TE/TI = 12.2/5.2/450ms, FA =  $20^{\circ}$ , B<sub>0</sub> = 1.5T) was interpolated to a three-fold oversampled grid by image domain zero-padding. Coil sensitivities were estimated using ESPIRiT<sup>4</sup> and the reproducing kernel of the multi-channel k-space was computed. Several sampling patterns were used for retrospective undersampling (R=4). For all sampling patterns, cardinal and power functions were computed on an oversampled and extended grid.

Results and Discussion: Figure 3 shows reconstructed images, power function and noise amplification in k-space for regular Cartesian, random and Poisson-disc sub-sampling. The power function predicts the interpolation error in k-space and the local Frobenius norm of the cardinal functions predicts noise amplification. Random sampling causes large holes in k-space which lead to high interpolation errors and noise amplification. This is avoided in Cartesian and Poisson-disc sampling, where the later can be used with compressed sensing.

**Conclusion:** Parallel imaging can be formulated as an approximation in a RKHS, which offers a theoretical framework for image reconstruction in k-space. The derived k-space metrics provide new insights into sampling.

## References:

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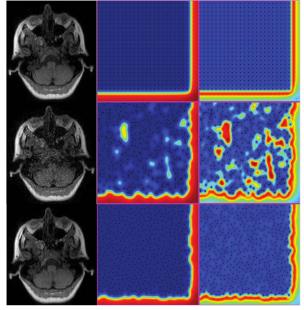


Figure 3 (color): From left to right: Reconstructed images, interpolation error in k-space (power function), and noise amplification in k-space for regular Cartesian (top) random (middle), and Poisson-disc (bottom) sampling patterns (black dots). Random sampling creates holes in k-space which lead to interpolation errors and noise amplification.