

# Regularized, Joint Estimation of $T_1$ and $M_0$ Maps

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## Introduction

Fast and accurate quantification of spin-lattice relaxation time  $T_1$  and proton density  $M_0$  and has been a longstanding goal in MRI research. The physical meaning of  $T_1$  maps can serve as a biomarker for subtle changes in pathology. Accordingly, relaxometry has recently gained attention as a method for monitoring the progression of disorders such Parkinson’s disease, epilepsy, and multiple sclerosis.

Classical methods such as inversion recovery (IR) and saturation recovery (SR) produce simple  $T_1$  estimates, but suffer from lengthy acquisitions. By contrast, steady-state pulse sequences are faster, but depend on more complex functions of both desired and nuisance parameters, causing naïve least-squares estimators to exhibit systematic error in low-signal regions. To improve  $T_1$  mapping precision, we propose a novel, model-based approach to this nonlinear estimation problem. Here, we focus on the Driven Equilibrium Single Pulse Observation of  $T_1$  (DESPOT1) sequence [1], though our statistical considerations can be adapted to other relaxometry techniques as well.

## Theory

We propose a model-based reconstruction framework for accurate  $M_0$  and  $T_1$  mapping from a DESPOT1 sequence. DESPOT1 repeats a spoiled gradient-recalled echo (SPGR) sequence over multiple flip angles, holding  $T_R$  and  $T_E$  constant. The steady-state signal model is given by

$$y_l^{(j)} = \frac{M_0^{(j)} \sin \alpha_l^{(j)} (1 - E_1^{(j)})}{1 - E_1^{(j)} \cos \alpha_l^{(j)}} + \epsilon_l^{(j)} \triangleq f(M_0^{(j)}, E_1^{(j)}, \alpha_l^{(j)}) + \epsilon_l^{(j)},$$

where  $y_l^{(j)}$  is the SPGR image data for the  $l$ th flip angle  $\alpha_l^{(j)}$ ;  $E_1^{(j)} \triangleq e^{-T_R/T_1^{(j)}}$ ;  $\epsilon_l \sim \mathcal{CN}\{0, \sigma^2\}$  is complex white Gaussian noise; and  $(j)$  indexes a specific voxel, without which the corresponding variable labels indicate vectorized versions across all voxels. Conventional methods typically neglect the noise term and recast this model into a linear form for least squares fitting. Unfortunately, this causes noise amplification in low-signal regions. We instead investigate  $T_1$  mapping as the following joint optimization problem:

$$\{\hat{M}_0, \hat{E}_1\} = \underset{\{M_0, E_1 \in [0,1]\}}{\operatorname{argmin}} \frac{1}{2} \sum_{l=1}^L \|y_l - f(M_0, E_1; \alpha_l)\|_2^2 + \beta_1 \sum_{k=1}^K \psi_k([\mathbf{C}M_0]_k) + \beta_2 \sum_{k=1}^K \psi_k([\mathbf{C}E_1]_k),$$

where  $y_l, M_0 \in \mathbb{C}^N$ ;  $\alpha_l, E_1 \in \mathbb{R}^N$ ;  $N$  is the number of voxels;  $\mathbf{C} \in \mathbb{R}^{K \times N}$  is a 2D spatial finite differencing matrix;  $\psi_k$  is a hyperbolic, edge-preserving potential function;  $k$  indexes the total  $K$  differencing operations; and  $\beta_1, \beta_2 \in \mathbb{R}$  are regularization parameters that control the level to which roughness in  $M_0$  and  $E_1$  is penalized, respectively. We iteratively solve this problem using an alternating minimization approach.

## Experiments and Results

We evaluated our method with data synthesized from the BrainWeb digital phantom [2]. Ground truth maps were converted to noise-corrupted data at a range of flip angles, including the two “ideal” angles postulated in [1], with  $T_R = 22.1\text{ms}$ ,  $T_E = 5.1\text{ms}$ . We first reconstructed the data with the conventional method [1], and then used this estimate to initialize the proposed reconstruction (Fig. 1). Comparisons with the ground truth are made in a normalized root mean-squared error (NRMSE) sense over voxels where  $M_0 > 0$ . Figure 2 shows that the proposed method reduces NRMSE of both  $M_0$  and  $T_1$  estimates over a wide range of SNR values and flip angle combinations (not shown).

We also provide *in vivo* results (Fig. 3) from an 8-channel receive array head coil in a 3T GE MRI scanner. We repeated an SPGR sequence at 5, 10, 20, 30, and 45 degree flip angles, with  $T_R = 19.8\text{ms}$ ,  $T_E = 5.1\text{ms}$ . We acquired 10 axial slices at 5mm thickness, with a 24cm FOV (256x256 matrix size). We reconstructed the data by both the conventional DESPOT1 and proposed model-based approaches. We selected several regions of interest for comparing parameter estimates. From the conventional method,  $T_1$  was measured as  $734 \pm 54\text{ms}$  and  $990 \pm 105\text{ms}$  in white and grey matter, respectively. With the proposed method,  $T_1$  was measured as  $802 \pm 17\text{ms}$  and  $1181 \pm 29\text{ms}$  in white and grey matter, respectively. These numbers highlight that the proposed method achieves higher precision *within* tissue types, while preserving high contrast *across* tissue types.

## Conclusions

We have described a statistical approach for joint reconstruction of  $M_0$  and  $T_1$  maps from DESPOT1 sequences. Our model-based method uses regularization to reduce conventionally common noise amplification issues. The proposed technique dramatically improves mapping precision and quality, both for synthetic and *in vivo* data, at a wide range of noise thresholds and flip angle combinations.

## Acknowledgments

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## References

[1] Deoni et al., MRM 49(3):515-26, 2003. [2] Collins et al., IEEE TMI 17(3):463-8, 1998.

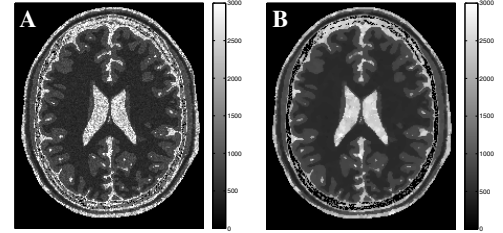


Fig. 1:  $T_1$  maps for simulated data at 40dB SNR, for “ideal” flip angles 5 and 30 degrees. [A] conventional. [B] proposed.

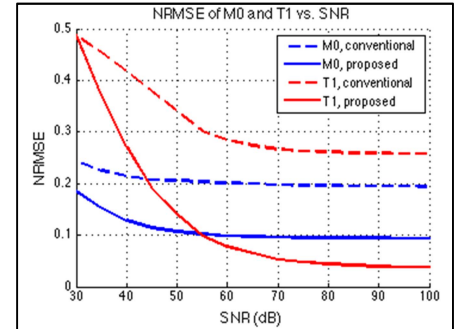


Fig. 2: NRMSE versus SNR of simulated data at “ideal” flip angles. Using more flip angles yields similar improvements.

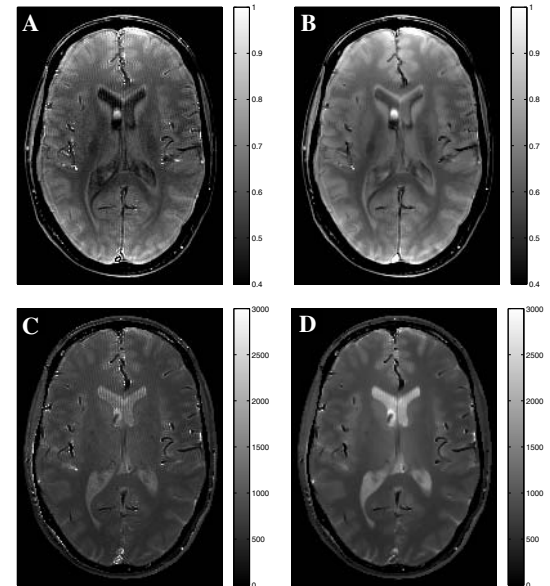


Fig. 3: Reconstructions from DESPOT1 sequence. [A]  $M_0$ , conventional. [B]  $M_0$ , proposed. [C]  $T_1$ , conventional. [D]  $T_1$ , proposed. Regularized estimation yields piecewise-smooth images. This translates to an increase in parameter mapping precision over the conventional methods.