## COMBINED FREE-BREATHING 3D LGE AND T1 MAPPING FOR SIMULTANEOUS ASSESSMENT OF SCAR AND DIFFUSED FIBROSIS

Sebastian Weingärtner<sup>1,2</sup>, Mehmet Akçakaya<sup>1</sup>, Warren J Manning<sup>1</sup>, and Reza Nezafat<sup>1</sup>

<sup>1</sup>Department of Medicine, Beth Israel Deaconess Medical Center and Harvard Medical School, Boston, MA, United States, <sup>2</sup>Computer Assisted Clinical Medicine, University Medical Center Mannheim, Heidelberg University, Mannheim, Germany

**INTRODUCTION:** Imaging of scar and diffuse fibrosis provides diagnostic and prognostic information in various cardiovascular diseases. Late gadolinium enhancement (LGE) using an inversion recovery sequence allows imaging of scar in the left ventricle (LV) (1).  $T_1$  mapping using Look-Locker based sequences provides information about diffuse fibrosis in the myocardium (2). LGE and  $T_1$  mapping images are usually using two different imaging acquired sequences. Conventionally, T<sub>1</sub> mapping is performed by acquiring a series of 2D multi-slice images in a single long breath-hold. Therefore, it requires numerous breath-holds for LV coverage. In this study, we sought to develop a combined 3D freebreathing LGE/T<sub>1</sub> mapping sequence for simultaneous evaluation of myocardial scar and fibrosis in a single exam.

METHODS: Fig. 1 shows the schematic of the proposed combined LGE/T<sub>1</sub> mapping sequence. Four inversion recovery determined  $T_{inv}$ , chosen to null the healthy myocardium. This dataset is additionally used to reconstruct the conventional LGE image. To reduce the

scan time, the three supplementary  $T_1$  weighted images, were undersampled by a factor of 3, g however the data for LGE was fully-sampled. To provide adequate spatial alignment among all images, which is necessary for the voxel-wise processing, the acquisition is performed with two interleaves. The first interleaf always acquires data for the LGE scan. The acquisition in the second interleaf cycles through the three  $\vdash$ supplementary scans with different inversion

times, leading to three undersampled k-spaces Fig. 2: Representative slices of combined free-breathing 3D LGE/T1 mappping sequence. (each with 3-fold acceleration). To avoid issues arising from insufficient longitudinal magnetization recovery, a saturation pulse was added right after the detection of each R-wave, which erases the magnetization history. Respiratory motion compensation for this sequence is performed in two phases: 1) The outer k-space parts are acquired using joint navigator (NAV)-gating of the two interleaves, i.e. a segment is accepted only if both interleaves are within the gating window. 2) The k-space centers of the four different images are acquired sequentially at the beginning of the scan with regular, prospective NAV gating. The dynamic acquisition of k-space centers improves imaging efficiency, since joint NAV-gating is not required.

Furthermore, we hypothesize that this dynamic acquisition of centers does not cause image misregistration, since it takes a relatively short scan time, and because the central k-space does not contain high-resolution details of the image.

**Reconstruction:** The 3-fold undersampled supplementary images are reconstructed with an improved compressed sensing algorithm (3). The LGE information is obtained from the fully-sampled data. The  $T_1$  maps are generated by a voxel-wise fit to the image intensity of all four images. The fit function is derived from the Bloch equations, incorporating the saturation pulse at the beginning of each heart cycle.

In-vivo Imaging: All imaging was performed on a 1.5T Philips Achieva system. In-vivo images were acquired in six healthy subjects in axial or short-axis view 5 to 20 minutes after contrast injection of Gd-BOPTA. An ECG-triggered free-breathing 3D GRE sequence was used for the proposed method with spatial resolution= $1.3 \times 1.3 \times 4$  mm<sup>3</sup>.

Comparison  $T_1$  maps were acquired using the conventional multi-slice 2D MOLLI Fig. 3: a) shows representative slices of the 3D  $T_1$  maps SSFP sequence (4) with resolution =  $1.7 \times 2.1 \text{ mm}^2$  and slice thickness = 10mm. **RESULTS:** Figure 2 shows multiple representative slices of an axial LGE image acquired is compared to a corresponding slice of the 2D MOLLI T<sub>1</sub> Map. using the proposed sequence seven minutes after contrast injection in the top row. The lower row shows the corresponding  $T_1$  maps. Figure 3 shows multiple representative slices of a short-axis 3D T<sub>1</sub> map acquired with the proposed sequence. The image acquisition of this case took 11 minutes for LV coverage. In Figure 3b, a single-slice of the 3D T<sub>1</sub> map is compared to a slice of a 2D MOLLI sequence. The proposed method achieves improved signal homogeneity in the  $T_1$  maps even at a higher spatial resolution (average reduction of the variance in the blood pools=37%). No significant difference was found between the  $T_1$  times of the two sequences for the blood pools or the myocardium (P > 0.76). The  $T_1$  times assessed with the

proposed sequence were 306.4±79.7ms in the myocardium, 193.5±60.8ms in the LV and 182.5±63.3ms in the RV. For reference the MOLLI sequence estimated  $T_1$  times of 314.1±59.9ms, 189.1±41.9ms and 185.7±45.7ms for the myocardium, the LV and the RV respectively. CONCLUSIONS: We have proposed a novel sequence that integrates high resolution 3D LGE imaging with 3D T<sub>1</sub> mapping. The T<sub>1</sub> maps generated using the proposed sequence are more homogenous and have improved spatial resolution and volumetric coverage compared to existing techniques. REFERENCES: 1. Kim, R.J. NEJM, 2000; 2. Messrohgli, D.R. Radiology, 2006; 3. Akçakaya, M. MRM, 2011; 4. Messrohgli, D.R. MRM, 2004;



images are acquired with different inversion times. The data Fig. 1: Sequence diagram depicting the interleaving of a fully-sampled LGE image and from all four images are used for estimating  $T_1$  maps by voxel- three undersampled supplementary  $T_1$ -weighted images. The LGE information is obtained wise curve fitting. One dataset is acquired using a pre- from Image #1, whereas Images #1 - #4 are used for the generation of the  $T_1$  maps.

T<sub>1</sub> Maps

Slice



(a)



Slice 11

Slice 19

h)

T<sub>1</sub> Maps

 $T_1(ms)$ 

800

600

400

200