

Three-Dimensional Image-based Navigator for 3D MR Coronary Angiography

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Introduction: Many respiratory motion compensation techniques have been proposed to correct for the respiratory-induced heart motion in cardiac MRI [1]. A right-hemidiaphragmatic navigator (NAV) is the most commonly used method that monitors the respiratory motion of the right-diaphragm along the superior-inferior (SI) direction with acceptance during a narrow gating window [2]. Recently, a two-dimensional (2D) image-based NAV has been presented to compensate for the respiratory motion of the heart along the SI and right-left (RL) directions, and to increase the size of the gating window [3]. In addition to the SI and RL motions, respiratory motion may also occur along the anterior-posterior (AP) direction [4, 5, 6]. In this study, we sought to develop and evaluate a 3D image-based NAV (3D-NAV) to estimate the respiratory motion along the three-directions to increase gating efficiency and improve image quality. Experiments using phantom and human studies were performed to investigate the proposed method.

Material and Method: A schematic diagram of the proposed method is shown in Fig. 1. Thirteen startup pulses of a balanced SSFP 3D MR coronary angiography sequence were modified to acquire a low resolution 3D-NAV at each cardiac cycle immediately before the acquisition of segmented k -space data. Gradients with a high to low profile-order were included in the startup pulse sequence to perform phase encoding in the slice and phase-encode directions. The 3D-NAV was then measured in the coronal orientation with frequency encoding in the SI direction. The spatial and temporal resolution of the 3D-NAV were approximately $1(\text{SI}) \times 56(\text{RL}) \times 18(\text{AP}) \text{ mm}^3$ and 60 ms, respectively. The 3D-NAVs were automatically segmented to extract the heart and registered to the first acquired 3D-NAV to estimate the relative bulk translational SI, AP, and RL motions. The estimated motions were used to retrospectively correct the phase of the subsequently acquired k -space data. To demonstrate the feasibility of the 3D-NAV, phantom and human studies were performed on a 1.5T CMR scanner (Philips Achieva) using the whole-heart 3D SSFP MR coronary angiography sequence with the following imaging parameters: FOV = $280 \times 280 \times 90 \text{ mm}^3$; voxel size = $1 \times 1.2 \times 1.2 \text{ mm}^3$; TR/TE/ α = $4.6/2.3/70^\circ$ and half-Fourier acquisition with a factor of 0.625. A body-coil and a 32 element cardiac coil array were used for the phantom and human studies, respectively. During the phantom experiment, scan was paused and the phantom was moved to create motion along three-directions. The motion was estimated using the 3D-NAV and corrected in the k -space data. The human study was performed on 5 healthy adult subjects (4 males, 30 ± 7 years) using the same MR coronary angiography sequence. The 3D-NAV was again used to retrospectively correct the respiratory-induced heart motion. A conventional MR coronary angiography image dataset (reference) was also acquired by gating and tracking the respiratory motion using the right-hemidiaphragmatic NAV with a 7mm gating window and 0.6 tracking factor. The reference, motion-corrupted, and motion-corrected images were scored by two blinded expert readers (1-poor, 4-excellent). Normalized vessel sharpness was calculated using Soap-Bubble [7] and a signed-rank test was used for comparison.

Results and Discussion: Fig. 2 shows the performance of the 3D-NAV in estimating and correcting the 3D motion in the phantom study. As shown, the motion-corrected image is very similar to the reference image. Fig. 3 and 4 display the efficacy of the 3D-NAV in two healthy subjects. As shown, the quality of motion-corrected images is further improved by correcting the motion along the three directions. The vessel sharpness and image scores for the reference and motion-corrected images along the three-directions were similar (Table 1) but with improved respiratory gating efficiency for the 3D-NAV (100% vs. $57 \pm 13\%$). The mean magnitude of estimated motion along the SI, AP, and RL directions was 3.7 ± 2.7 , 2.3 ± 1.9 , and $1.9 \pm 0.8 \text{ mm}$.

Conclusions: A novel 3D-NAV for 3D MR coronary angiography is presented. This technique allows for the correction of respiratory-induced heart motion along the SI, AP, and RL directions, thereby facilitating reduced scan time without compromising image quality.

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References: [1] Scott, Radiology, 2009; [2] Wang, MRM, 1995; [3] Henningsson, MRM, 2012; [4] Nehrke, MRM, 2003; [5] Keegan, JMRI, 2007; [6] Lai, MRM, 2009; [7] Etienne, MRM, 2002.

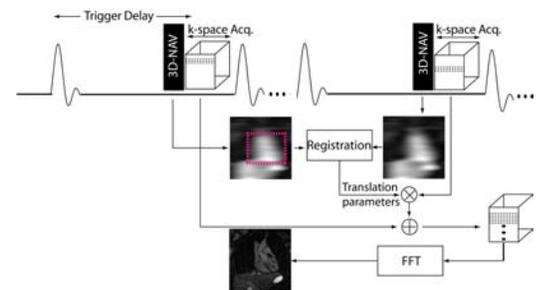


Fig.1: Schematic diagram of the proposed motion compensation method (3D-NAV).

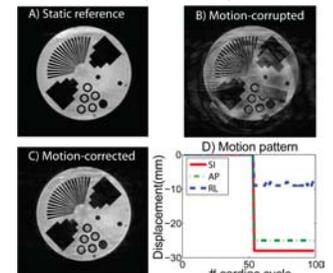


Fig.2: Performance of the 3D-NAV on the estimation and correction of a 3D motion in the phantom study.

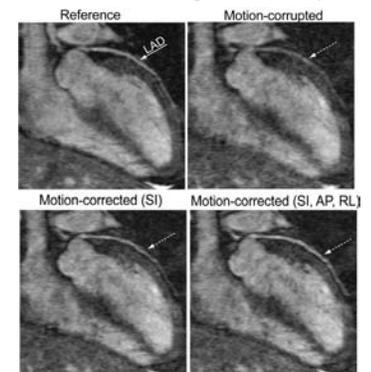


Fig.3: Reformatted left coronary artery images acquired from a healthy female subject.

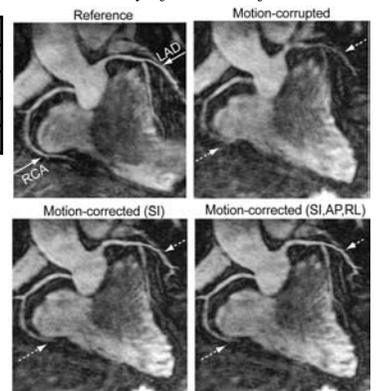


Fig.4: Reformatted left and right coronary artery images acquired from a healthy male subject.

Method	Vessel sharpness		Visual grading	
	RCA	LAD	RCA	LAD
Reference	0.46 ± 0.09	0.50 ± 0.07	3.60 ± 0.52	3.60 ± 0.52
3D-NAV	0.50 ± 0.01	0.54 ± 0.03	3.60 ± 0.52	3.60 ± 0.52
corrupted	0.39 ± 0.24	0.33 ± 0.19	3.10 ± 0.57	2.80 ± 0.79

Table 1: Normalized vessel sharpness and visual grading.