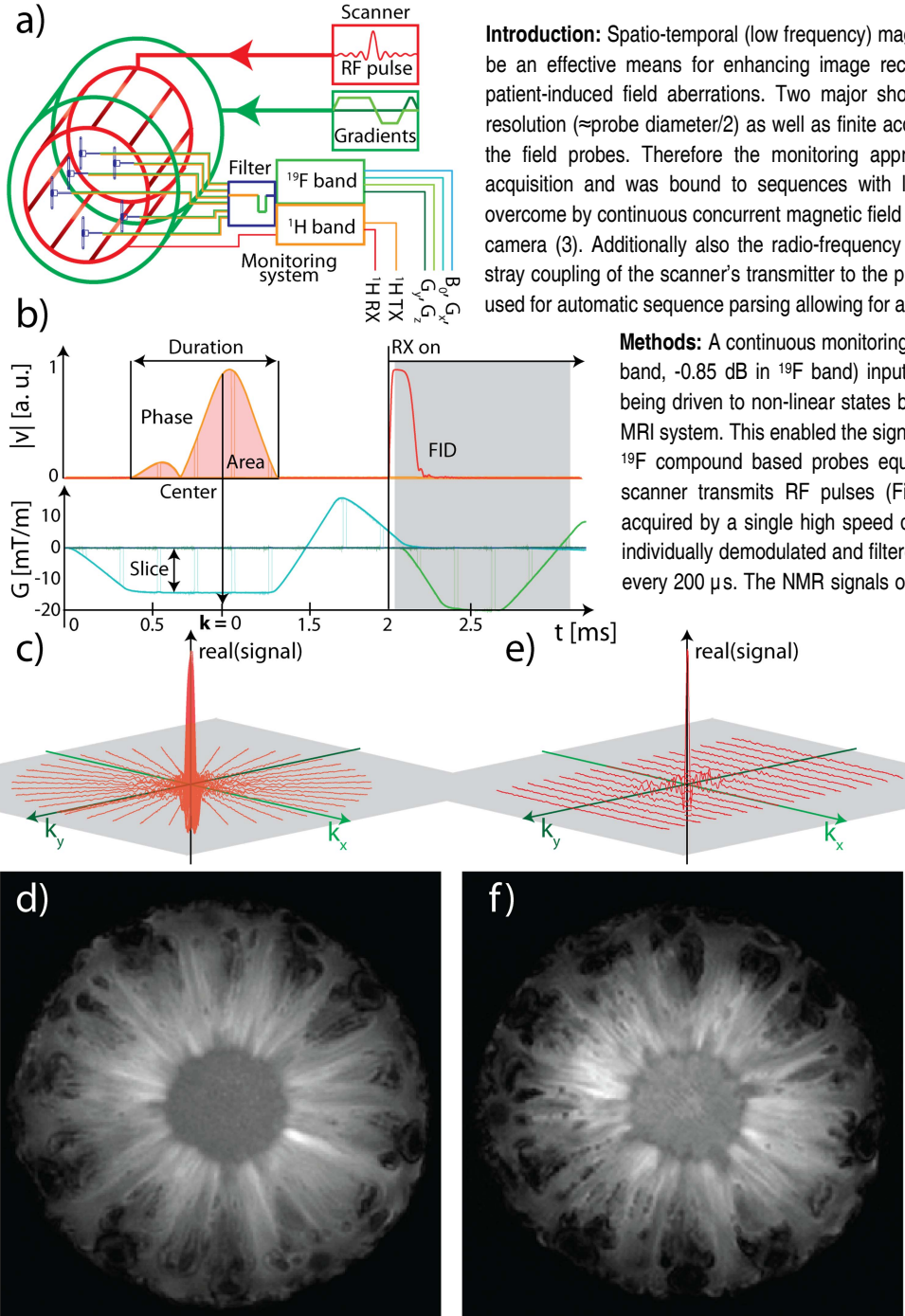


Automatic Reconstruction of Gradient Echo Imaging Sequences by Concurrent and Continuous Monitoring of Gradient and RF Waveforms

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Introduction: Spatio-temporal (low frequency) magnetic field monitoring by NMR field probes¹ was shown to be an effective means for enhancing image reconstruction in situations of imperfect encoding fields or patient-induced field aberrations. Two major shortcomings of conventional monitoring are limited image resolution (\approx probe diameter/2) as well as finite acquisition and dead time due to the relaxation properties of the field probes. Therefore the monitoring approach needed to be closely entangled with the image acquisition and was bound to sequences with low repetition times. In this work these constraints are overcome by continuous concurrent magnetic field monitoring² based on a continuous ¹⁹F NMR dynamic field camera (3). Additionally also the radio-frequency (RF) fields were acquired by the camera³ exploiting the stray coupling of the scanner's transmitter to the probe channels. The information on RF field dynamics was used for automatic sequence parsing allowing for automatic reconstruction of various sequences.

Methods: A continuous monitoring system² was complemented by narrow band (-20dB in ¹H band, -0.85 dB in ¹⁹F band) input filters protecting the first stage low noise amplifier from being driven to non-linear states by the stray coupled high power RF transmit pulses of the MRI system. This enabled the signal acquisition from heavily doped ($T_2 \sim T_1 \sim 150 \mu s$, $\phi 2.2 mm$) ¹⁹F compound based probes equipped with low-eddy current RF shields even while the scanner transmits RF pulses (Fig. a). The ¹⁹F and the ¹H band were simultaneously acquired by a single high speed digitizer per probe channel. Subsequently both bands are individually demodulated and filtered to 1 MHz bandwidth. The field probes were re-excited every 200 μs . The NMR signals of the sample were acquired by a separate digitizer hosted in the monitoring spectrometer via a T/R head coil.

The monitored ¹H transmit signal was parsed for the excitation pulses whose phase and the magnetic center was determined automatically. The magnetic center of the pulse set the k-space origin from which the trajectory was calculated by a band-limited extrapolation of the gapped (due to re-excitation) probe data (Fig. b). The MR signal acquired from the subject was phased according to the excitation pulse's phase and gridded according to the concurrently monitored k-space trajectory.

Standard protocols for RF spoiled 2D UTE (TR/TE=30/0.9ms) and Cartesian gradient echo (30/2ms) with 1 mm in-plane resolution were performed on a Achieva 7T system (Philips, Cleveland, USA).

Results: Fig b) shows the monitored gradient fields (before and after interpolation), the RF excitation pulse and the recorded FID for the UTE. c) and e) show the MR signal gridded to the monitored k-space (every 20th echo is plotted). (UTE d) and (Cartesian f) show the finally reconstructed images of a pineapple, no filters were applied.

Discussion: Solely the knowledge that a gradient echo (GRE) is generated after each RF pulse is

injected into the reconstruction. All remaining required information –actually a comprehensive description of the spin evolution in the system – is extracted from the dynamic field camera. This capability opens up the possibility of unifying image reconstruction for a large class of sequences, as shown here for GRE acquisitions. Also, continuous concurrent low-frequency and RF field monitoring fully disentangles the monitoring process from MR sequencing and signal acquisition, rendering its integration trivial, both from a sequence and acquisition methods perspective. Concurrent RF pulse monitoring could potentially also be used to perform signal amplitude correction or rejection of corrupted profiles, making up for transmit pulse fluctuations and drifts.

References: 1) Barmet et al. MRM 2008, 2) Dietrich et al ISMRM 2011, 3) Dietrich et al ISMRM 2012