

# Volumetric $R_2^*$ mapping using 3D z-shimmed single scan multi-echo gradient-echo imaging

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**Introduction** Accurate  $R_2^*$  ( $=1/T_2^*$ ) value quantification is required for many applications [1]. Multi-echo GRE imaging method is generally used to evaluate  $R_2^*$  value. However, the main drawback of this method is the influence of macroscopic  $B_0$  inhomogeneity which occurs as unintended phase dispersion. This unintended phase dispersion is transformed as signal loss in image space. Z-shim method using compensation gradient in slice selection direction is used to overcome the problem [2,3]. This method is usually performed in 2D GRE imaging. 3D GRE imaging is inherently less sensitive to macroscopic  $B_0$  inhomogeneity than 2D GRE imaging, but they are still problematic in frontal region and long TE. To solve these problems, 3D z-shim method with extended  $k_z$ -space sampling was introduced [4]. In this study, we propose 3D z-shim method using multi-echo GRE imaging for volumetric  $R_2^*$  quantification. The method uses a multi-echo approach, therefore no additional scan times are required compared to 3D GRE sequences.

**Theory & Methods** Figure 1 shows the  $k_z$ -space acquisition trajectory during echo time and  $G_z$  gradient timing diagram of our proposed 3D z-shim multi-echo GRE pulse sequence. For odd echoes, the acquisition trajectory is the same as normal 3D GRE imaging, but for even echoes, we acquire shifted  $k_z$ -space data in positive  $k_z$  direction. Note that since the influence of macroscopic  $B_0$  inhomogeneity increases as the echo time increases, the z shim gradient is increased for subsequent echoes. This is represented in the shifted increase of  $k_z$ -space coverage for even echoes.

3D z-shim multi-echo GRE images (3.0T Siemens Tim Trio, 32 slice/slab, voxel size:  $1.2 \times 1.2 \times 2.5 \text{ mm}^3$ , TR:40ms, TE= $4.476+(n-1) \times 3.880$ ms for 9 echoes ( $n=1,2,\dots,9$ ), flip angle:  $12^\circ$ , BW: 389Hz/px, scantime:4m) using the proposed acquisition strategy were acquired from a healthy volunteer. To generate  $R_2^*$  map, we divide into two echo sets. One using even echoes (2,4,6,8 echoes) and the other using odd echoes (1,3,5,7,9 echoes). In other words, we calculate  $R_2^*$  using even echoes in the regions with macroscopic  $B_0$  inhomogeneity, and calculate  $R_2^*$  using only odd echoes in homogeneous regions. Afterwards, we combine the two  $R_2^*$  maps evaluated for each region to create whole  $R_2^*$  map. A mono-exponential fitting was used for  $R_2^*$  calculations.

**Results** Figure 2 shows the acquired magnitude images from the proposed 3D z-shim pulse sequence. Figure 2a and c correspond to normal 3D multi-echo GRE images. Thus, two images show volumetric signal losses in regions of  $B_0$  inhomogeneity. However, Fig 2.b shows that the proposed 3D z-shim method successfully restores the volumetric signal losses in the frontal and temporal regions.

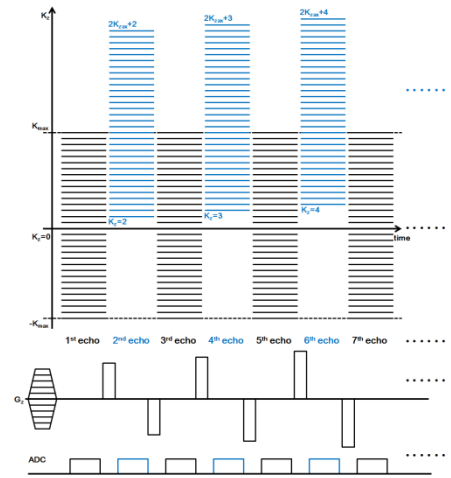
The uncorrected volumetric  $R_2^*$  map is shown in Fig 3a. Overestimation of the  $R_2^*$  values is apparent in regions of  $B_0$  inhomogeneity. Corrected  $R_2^*$  maps using the proposed approach is shown in Fig. 3b for the volumetric region showing improved quantification. The effective shift of  $k_z$  center (at TE= $35.516$ ms) is shown in Fig. 3c. Our results show that we can correct  $k_{z\text{off}}$  shifts, in the range of approximately -10 to 40 echo shift in  $k_z$ -direction, as shown in Fig. 3c. However, the present method cannot correct for  $k_{z\text{off}}$  shifts that exceed this maximum coverage.

**Conclusion** We have presented a volumetric  $R_2^*$  map including which corrects for macroscopic  $B_0$  inhomogeneity. The methods use a multiecho GRE approach with increasing field inhomogeneity compensation gradient and does not require additional scan time.

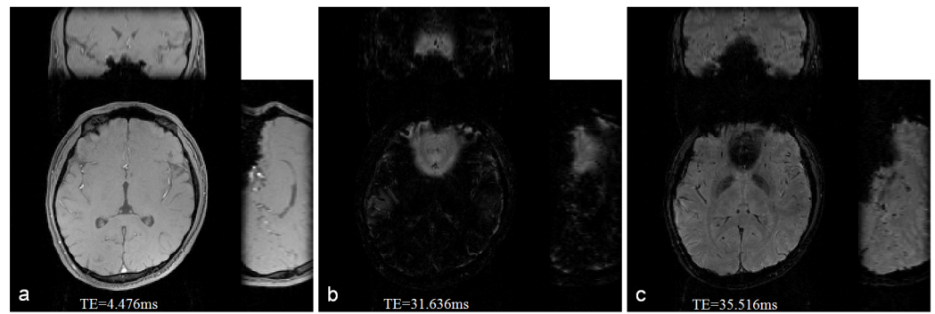
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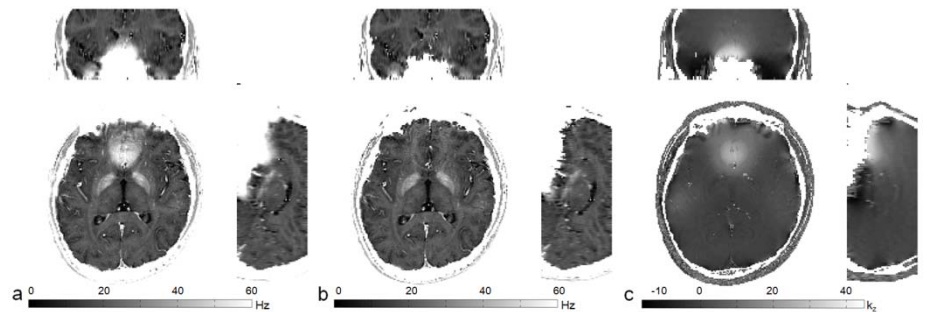
**References** [1] Haacke et al. (2005) MRI, 23:1-25 [2] Yang et al. (1997) MRM, 37:331-335 [3] Meng et al. (2008) MRM, 60:1388-1395 [4] Glover (1999) MRM, 42:290-299



**Figure 1.** The acquisition strategy in  $k_z$ -space and pulse sequence timing diagram showing the compensation  $G_z$  and ADC. The rest of timing diagram is same as a normal 3D GRE method.



**Figure 2.** Magnitude images acquired using the proposed method. a. First echo image (at 4.476ms), b. Eighth echo image (at 31.636ms), c. Ninth echo image (at 35.516ms).



**Figure 3.** a. Uncorrected volumetric  $R_2^*$  map, b. Corrected volumetric  $R_2^*$  map, c. The evaluated  $k_{z\text{off}}$  map at 35.516ms.