

Comparing two atlas-based automatic segmentation methods for subthalamic nucleus deep brain stimulation

Y. Xiao¹, L. Bailey¹, M. Mallar Chakravarty², S. Beriault¹, A. F. Sadikot³, G. Bruce Pike¹, and D. Louis Colins¹

¹McConnell Brain Imaging Centre, Montréal Neurological Institute, McGill University, Montréal, Québec, Canada, ²Kimel Family Translational Imaging-Genetic Laboratory, Research Imaging Centre, Centre for Addiction, Toronto, Canada, ³Division of Neurosurgery, McGill University, Montréal, Canada

Introduction: Deep brain stimulation (DBS) of the subthalamic nucleus (STN) is an effective treatment for Parkinson's disease (PD). Since the STN has a small size and is divided into three functional regions (motor, associative and limbic), it is important to localize the stimulation target to avoid undesirable side-effects and achieve the best therapeutic benefits for the patients. Previously, automatic segmentation of the basal ganglia nuclei was achieved through non-rigid histological atlas warping [1,2]. In this abstract, this method is compared with a novel *in vivo* T2 data derived atlas warping strategy for their segmentation performance on the STN, red nucleus (RN), and substantia nigra (SN). The manual segmentations of these three nuclei from the susceptibility-based 3T MR images were used as a silver standard for evaluation.

Methods: After providing informed consent, 2 healthy subjects (male, 24yr & female, 41yr) and 4 PD patients (1 female, 3 male, age = 56±6yr) volunteered for the study. Each subject was scanned on a 3T MRI scanner (Siemens Trio, Erlangen, Germany) with a 10 echo 3D FLASH MRI protocol: TE={1.6, 4.1, 6.6, 9.1, 13.0, 16.0, 18.5, 21.0, 23.5, 26.0}ms, TR=30ms, flip-angle=23°, BW=±450 Hz/pix, matrix=256x256, 176 sagittal slices, resolution= 0.95x0.95x0.95mm³, 6/8 partial Fourier in the phase and slice encoding directions, and GRAPPA=2. From the MRI data acquired, three image contrasts (T1w image, T2*w image, and R2* map) were generated. The T1w image was produced by averaging the magnitude images of the first four echoes. The T2*w image was generated by averaging the magnitude of the last five echoes. The R2* map was derived by fitting all magnitude data to an exponential curve. With ITK-SNAP (www.itkSNAP.org), we obtained the silver standard by manually segmenting the STN, SN, and RN on each subject in 3D using a consensus of their T2*w images and R2* maps. The first atlas-based segmentation method (referred to as "AS1") was described in [2] where histological data, structural outlines and a T1w single subject average MRI known as Colin27 [3], are non-linearly warped to a patient's T1w volume to achieve segmentation. In the second method ("AS2"), the atlas structures are obtained by manually painting the STN, SN, and RN on the Colin12 T2w image, a single subject average of 12 T2w volumes [3], co-registered with the Colin27 T1w image. Segmentation in AS2 is achieved by warping the T2w-defined labels using the transforms estimated in AS1. AS1 and AS2 segmentations are compared to the silver standard manual labels with three metrics: 1) the overlap metric $\kappa=2*a/(b+c)$, where **a** is the mutual volume of two segmentations, and **b** and **c** are volumes belong to each segmentation; 2) the Euclidean distance (COM_Euclid) between the centre of mass (COM) of the deformed atlas labels and manual segmentation; and 3) the x-, y-, and z-coordinate COM differences (COM{x,y,z}=COM_{atlas} - COM_{manual}) after transforming them into Talairach space.

Results: Three metrics are presented in Table 1 with the mean values and standard deviations of all 6 subjects.

	Left RN			Right RN			Left SN			Right SN			Left STN			Right STN		
Kappa	0.56±0.08 / 0.70±0.06			0.50±0.11 / 0.72±0.08			0.58±0.04 / 0.54±0.04			0.61±0.01 / 0.57±0.09			0.55±0.08 / 0.55±0.07			0.41±0.17 / 0.53±0.07		
COM_Euclid(mm)	1.72±0.40 / 1.24±0.42			2.35±0.56/ 1.06±0.54			2.08±0.67/ 2.56±0.30			1.65±0.73/ 2.07±0.69			1.64±0.63/ 1.35±0.42			2.66±0.96/ 1.52±0.63		
COM{x,y,z}(mm)	x	y	z	x	y	z	x	y	z	x	y	z	x	y	z	x	y	z
	-0.28± 0.54	-1.50± 0.24	-0.89± 0.37	1.68± 0.73	-0.86± 0.37	-1.52± 0.32	1.58± 0.49	1.49± 0.48	0.44± 0.43	-1.00± 0.44	1.29± 0.62	0.33± 0.38	-1.29± 0.53	0.09± 0.99	-0.62± 0.52	1.91± 1.20	-0.39± 0.90	-1.60± 0.47
	0.32± 0.53	0.97± 0.44	0.68± 0.35	-0.23± 0.77	0.60± 0.51	0.58± 0.32	0.38± 0.55	-2.44± 0.54	0.72± 0.37	0.11± 0.36	-2.00± 0.75	0.70± 0.20	0.26± 0.64	0.79± 1.06	0.52± 0.66	0.35± 1.07	0.34± 0.98	0.60± 0.56

Table 1. The mean value and standard deviation for the three metrics (**black**=AS1, **blue**=AS2). Please note that for COM{x,y,z}, x-coordinate = left-right direction, y-coordinate=anterior-posterior direction, and z-coordinate=superior-inferior direction.

Conclusion: Overall, there is a coarse correspondence between AS1 and AS2 segmentations and the manual segmentation, but the performance of each segmentation method differ for various structures. First, the kappa metric shows that AS2 performs significantly better than AS1 for the RN ($p<0.02$), and on average better for the right STN. Their performances does not differ significantly for other structures. Second, the COM Euclidean distances of AS1 segmentations and manual segmentations are on average larger than that for AS2 on the RN and STN, significantly so for the right RN and STN ($p<0.05$). As the "key" structure of DBS, AS2 offers a comparable or better segmentation for the STN bilaterally. Through the analysis of the x-, y-, and z-coordinate COMs positions, the AS1 segmentation was more lateral and superior than the silver standard STN ($p<0.05$), more medial and posterior for the SN ($p<0.01$), and more anterior and superior for the RN ($p<0.01$); On the other hand, AS2 segmentation was more posterior and inferior for the RN ($p<0.01$), and more anterior and inferior for the SN ($p<0.01$). In summary, the Colin12 T2w-image-defined atlas was more successful in the group we studied.

Discussion: Notably, the segmentation of the right STN for AS1 method was significantly worse than that of the left STN in terms of kappa and COM Euclidean distances ($p<0.05$), but no significant difference in bilateral segmentation of the STN was found in AS2. This could be explained by the fact that the histological atlas (AS1) was defined symmetrically while there was no such assumption for AS2. In our subjects, the averaged left STN size was larger than the right, and Colin27 left STN is also larger than the right as shown in the T2w image. AS2's better performance on the RN, and its worse mean COM Euclidean distances on the SN suggest that the T1w-T1w inter-subject or pseudo-MRI-to-subject registration may not fully account for the variability in these nuclei [4] that are almost invisible on the T1w images. In AS1, the histologically defined STN has a relatively small size (left-right-averaged: 170 mm³), and for AS2, the *in vivo* data derived atlas has a relatively smaller SN (left-right-averaged: 484 mm³) than the averages of the studied population (left-right-averaged RN: 224 mm³; left-right-averaged SN: 527 mm³). As a result, without proper constraints, these biases from the single subject defined atlas could not be fully neutralized during the mapping to different subjects, resulting in sub-optimal segmentations. Moreover, the neuron loss in PD subjects may further enhance this atlas-inherent bias since most of the currently used atlases were obtained from healthy subjects. As a result, incorporating image contrasts that can visualize these structures should be instrumental to the more accurate automatic segmentation of the SN, RN, and more particularly the STN.

Reference: 1. Chakravarty *et al.* NeuroImage 30 (2006) 359–376; 2. Chakravarty *et al.* Med. Image Anal. 12 (2008) 713–726; 3. Holmes *et al.* J Comput Assist Tomogr. 1998 Mar-Apr; 22(2): 324-33; 4. Daniluk *et al.* Acta Neurochir (2010) 152:201–210.

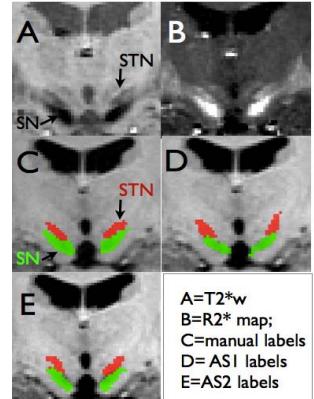


Figure 1. SN and STN of a 41 yo healthy female subject