

Isotropic Mapping of T_1 , T_2 , and M_0 with MP-DESS and Phase-Graph Data Fitting

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Introduction: Quantitative MRI (qMRI) of the human brain provides important insights into certain pathologies [1]. Isotropic, high resolution is best achieved with a 3D sequence – i.e. a 2D phase encoded (PE) acquisition – using short TR ($<T_2$). This leads to biased parameter estimates in qMRI approaches where perfect spoiling is assumed [2], for instance Look-Locker approaches. Thus, it is important to incorporate transverse relaxation into the signal equation, as has been carried out in transient balanced SSFP [3-4], which is however prone to banding artefacts induced by B_0 -inhomogeneities. Here, a double echo steady state sequence [5] with magnetization preparation, MP-DESS, is utilized to overcome these limitations. An accurate signal equation for least squares data fitting is provided by the extended phase graph [6]. Along the MP-recovery the DESS images, S^+ and S^- , are individually reconstructed. The S^+ state (the “FID”) provides a higher SNR whereas the S^- state (the “Echo”) has a more pronounced T_2 weighting. Together they provide high sensitivity for the parameters under investigation, i.e. M_0 , T_1 , and T_2 .

Methods: In a standard 3D-DESS sequence with rectangular pulses of flip-angle α , every Nth pulse is replaced by a rectangular 180° pulse. The recovery echo train of length N is divided in L segments of size M which encode the same k-space, giving $L=N/M$ different images for S^+ and S^- , respectively (Fig. 1). The outer MP loop has to be performed $N_x N_y / M$ times, where $\{N_x, N_y\}$ denote the PE matrix size. The signal is modelled with the extended phase graph. Since performing these calculations on a voxel-by-voxel basis for data fitting is far too slow, a parallelised computation matching the sequence parameters is pre-calculated on a suitable grid $\{T_1, T_2, W_{RF}\}$, where W_{RF} denotes a spatial B_1 weighting factor, common for the α -pulse and the 180° pulse. This results in a “signal database”, $\{\hat{S}_i^+, \hat{S}_i^-\}$, $i = 1, \dots, L$, showing a smooth dependence on the relaxation times.

M_0 is a common scaling factor of the signal levels. The signal database is well-suited for rapid tri-linear interpolation in least-squares cost function minimisation: $CF = \sqrt{\sum_{i=1}^L (s_i^+ - \hat{s}_i^+)^2 + (s_i^- - \hat{s}_i^-)^2}$. Consequently, the

fitting of $\approx 10^6$ voxels needs less than five minutes on an up-to-date desktop PC. Data were acquired on a Siemens TIM-Trio scanner with a 12-channel head array coil (Siemens, Erlangen). W_{RF} was mapped with the 3D AFI sequence [7] (TR1/TR2=5). Receiver sensitivity was corrected by means of a body-coil FLASH image. MP-DESS echo trains were acquired for an agarose phantom and the fitting result compared to spectroscopic measurements of T_1 and T_2 . Finally, an *in vivo* whole brain MP-DESS acquisition was performed and T_1 , T_2 , and M_0 maps were calculated. The MP-DESS sequence parameters were as follows: matrix size=160x160x120, flip-angle $\alpha = 10^\circ$, resolution = 1.4 mm (isotropic), TR/TE_{S+}/TE_{S-} = 10/3/7 ms, bandwidth = 270 Hz/Pixel, N/L = 360/9, parallel imaging acceleration = 2, and the acquisition time totalled 15 minutes.

Results: Example slices of the MP-DESS signal database are depicted in Fig. 2a, showing a smooth signal variation with relaxation times. From these the cost function is calculated, shown in Fig. 2b for target parameters $T_1/T_2=1000/100$ ms. It displays a pronounced global minimum enabling robust parameter estimation in the presence of noise. Fig. 3 compares the echo train measurement and the computed signal amplitudes, showing a nearly perfect match between phantom data and the phase graph signal description. The fitted relaxation-time estimates, $T_1/T_2=1683/83$ ms, agree with the gold standard spectroscopic evaluation to less than 3% and 8% for T_1 and T_2 , respectively. MP-DESS *in vivo* images and parameter mapping results are plotted in Fig. 4. Estimation of cortical relaxation times and the relative spin density agree well with the literature [8].

Conclusion: This work presents a novel method for accurate, 3D, high-resolution parameter mapping with time efficient data acquisition, as the MP-DESS sequence and the corresponding phase-graph signal model do not rely on any inter-sequence recovery dead-times. Although the echo train resembles an inversion recovery, the sequence is best understood as generating N different steady states through inversion/refocusing pulses replacing every Nth α -pulse. MP-DESS acquires B_0 -insensitive and artefact-free images, as opposed to fully balanced SSFP. Utilising non-selective RF pulses increases the mapping accuracy, as they allow for fast and robust mapping of the B_1 with AFI [7]. The S^+ and S^- images provide a robust cost function minimisation which is shown to be most accurate at low flip-angle α . The latter reduces MT effects and supports high field applicability.

References: [1] Shah et al, NeuroImage 2008:41:706. [2] Neeb et al, NeuroImage 2008:42:1094. [3] Scheffler, MRM 2003:49:781. [4] Schmitt et al, MRM 2004:51:661. [5] Redpath, MRM 1988:2:224. [6] Hennig, Concepts MR 1991:3:125. [7] Nehrke, MRM 2009:61:84. [8] Oros-Peusquens et al, MAGMA. 2008:21:131.

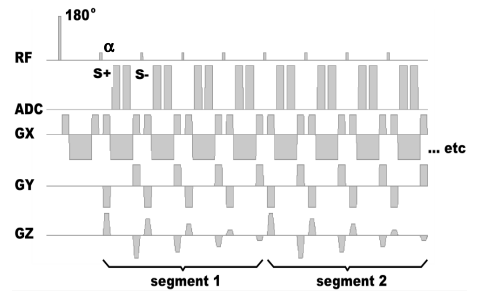


Fig. 1: MP-DESS Sequence diagram with $N=8$ and $L=2$, i.e. $M=4$ phase encode steps per segment.

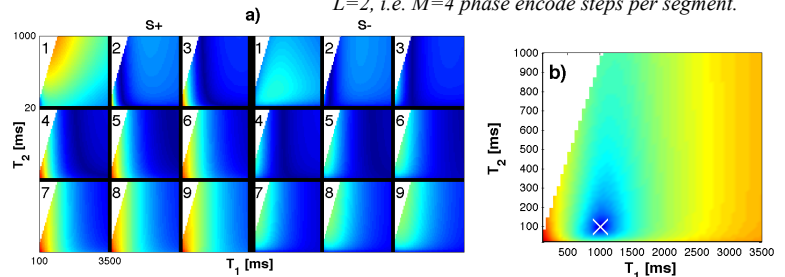


Fig. 2: a) MP-DESS signal database at $W_{RF} = 1$ ($\alpha=10^\circ$, refocusing pulse = 180°). b) Cost function at target $T_1/T_2=1000/100$ ms. Colours denote (arbitrary) units of signal amplitude.

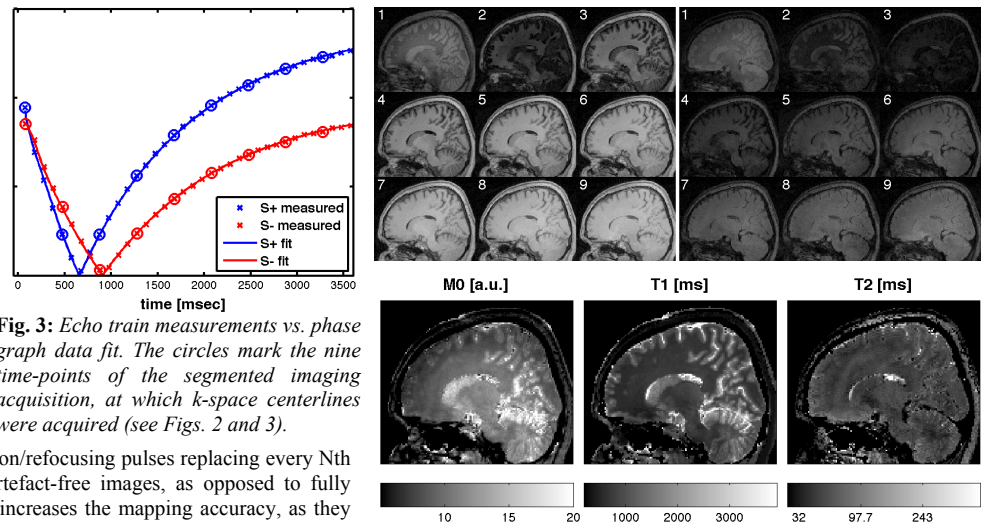


Fig. 3: Echo train measurements vs. phase graph data fit. The circles mark the nine time-points of the segmented imaging acquisition, at which k-space centerlines were acquired (see Figs. 2 and 3).

Fig. 4: Top: MP-DESS images of nine time-points along the recovery curve (left S^+ ; right S^-). Bottom: the fitted parameter maps.