

Spatiotemporal Denoising of MR Spectroscopic Imaging Data by Low-rank Approximations

H. Nguyen¹, X. Peng^{2,3}, M. Do⁴, and Z-P. Liang⁴

¹Department of Electrical & Computer Engineering, University of Illinois at Urbana-Champaign, Urbana, IL, United States, ²School of Electronic Information, Wuhan University, China, People's Republic of, ³Department of Electrical & Computer Engineering, University of Illinois at Urbana-Champaign, United States, ⁴Department of Electrical & Computer Engineering, University of Illinois at Urbana-Champaign, United States

INTRODUCTION

Low signal-to-noise ratio (SNR) has been a major limitation for magnetic resonance spectroscopic imaging (MRSI). A straightforward way to improve the SNR of MRSI data is to acquire more signal averages but at the expense of lengthening the already long data acquisition time. Several post-processing methods have been proposed to reduce noise in MRSI data, either by applying general denoising methods such as wavelet shrinkage or by imposing a specific parametric model for MRS signal [1-3]. This paper presents a novel denoising method, called LORA (LOw Rank Approximations), which exploits two low-rank properties of MRSI data: one due to partial separability and the other due to linear predictability of MRSI signals.

THEORY

The measured noise-corrupted MRSI data can be expressed as

$$\hat{s}(k, t) = s(k, t) + \xi(k, t),$$

where $s(k, t)$ represents the noiseless data and $\xi(k, t)$ is the measurement noise. We propose to denoise $\hat{s}(k, t)$ by exploiting the following low-rank structures:

a) *Low-rankness due to partial separability*: $s(k, t)$ can be approximated as partially-separable to the N -th order as

$$s(k, t) = \sum_{n=1}^N c_n(k) \phi_n(t). \quad (1)$$

Expression (1) implies that the Casorati matrix C formed from $s(k_n, t_m)$ (see equation (2)) has at most rank N [4]. In practice, N is much smaller than the size of the matrix.

$$C = \begin{bmatrix} s(k_1, t_1) & s(k_1, t_2) & \cdots & s(k_1, t_M) \\ s(k_2, t_1) & s(k_2, t_2) & \cdots & s(k_2, t_M) \\ \vdots & \vdots & \ddots & \vdots \\ s(k_{N_v}, t_1) & s(k_{N_v}, t_2) & \cdots & s(k_{N_v}, t_M) \end{bmatrix}; \quad H = \begin{bmatrix} s(t_1) & s(t_2) & \cdots & s(t_K) \\ s(t_2) & s(t_3) & \cdots & s(t_{K+1}) \\ \vdots & \vdots & \ddots & \vdots \\ s(t_{M-K+1}) & s(t_{M-K+2}) & \cdots & s(t_M) \end{bmatrix} \quad (2)$$

b) *Low-rankness due to linear predictability*: The ideal signal of a spin system with L spectral components resonating at frequency f_i with damping factor α_i can be expressed as

$$s(t_m) = \sum_{l=1}^L a_l e^{-(\alpha_l + j2\pi f_l)t_m}. \quad (3)$$

In practice, non-Lorentzian resonances occur but can be well approximated by (3) with a large order L . It follows from (3) that the Hankel matrix H formed from $s(t_m)$ (see equation (2)) has rank L .

c) *Algorithm*: Exploiting above described low-rank properties of MRSI data, we can effectively denoise $\hat{s}(k, t)$ by finding an optimal rank- N approximation of C and optimal rank- L approximation of H . This can be easily done with SVD. The specific algorithm is summarized below:

1. Given noisy data $\hat{s}(k_n, t_m)$, construct matrix C according to (2) and perform SVD truncation to obtain its N -th rank approximation C_N .
2. Take the discrete Fourier transform along each column of C_N to obtain $\bar{s}(r_n, t_m)$.
3. For each voxel r_n , form matrix H from $\bar{s}(r_n, t_m)$ and obtain its L -th rank approximation H_L .
4. The denoised data is then obtained by extracting the elements from the first row and last column of H_L .

METHODS

We applied the proposed denoising method to in-vivo MRSI data of the mouse brain, which was previously used in [5]. The CSI data was acquired using Varian INOVA 11.74 T (500 MHz) MRI system, TE=270 ms, TR=1500 ms, bandwidth=6000 Hz, 1024 FID data points for each of 32×32 k -space samples, and 8 averages. A detailed description of the dataset can be found in [5].

RESULTS

Figure 1 shows a typical set of results. It is clear that with LORA, noise has been effectively suppressed while spatial and spectral features were preserved. In particular, the denoised spectrum at a particular voxel shown in Fig. 1(b) clearly shows the resonances of residual water and metabolite peaks with reduced noise variance; the denoised spatial distribution obtained by integrating the complex spectrum from 1.6 ppm to 2 ppm has well-preserved spatial features in the electrocoagulation and CSF regions.

CONCLUSIONS

A new method for spatial-spectral denoising of MRSI data has been presented. The method exploits two low-rank properties in MRSI data, one due to partial-separability and the other due to linear predictability of MRSI data. Experimental results from practical data demonstrate that the method is effective in reducing noise in MRSI data in a wide range of SNR values.

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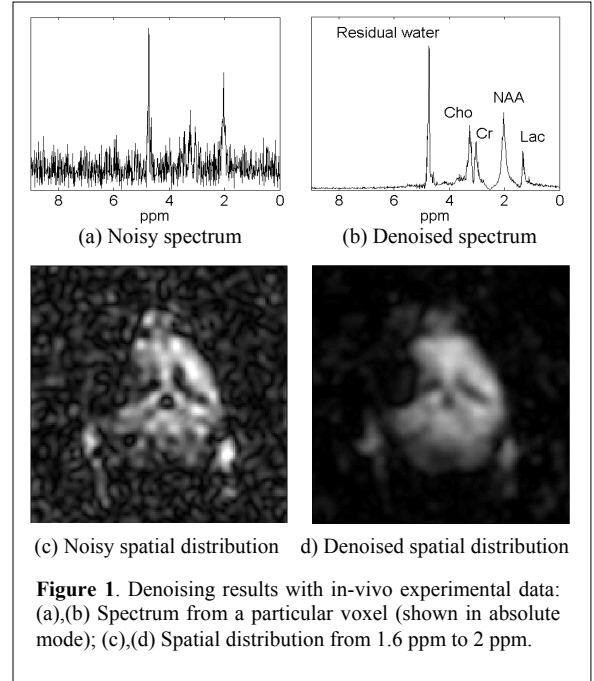


Figure 1. Denoising results with in-vivo experimental data: (a),(b) Spectrum from a particular voxel (shown in absolute mode); (c),(d) Spatial distribution from 1.6 ppm to 2 ppm.