

A quantitative approach of extracting magnetic moments in small cylindrical object

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Introduction: Susceptibility is key to revealing information about oxygenation saturation levels, calcium and iron. We have developed a complex sum method that can be used to determine magnetic susceptibility of narrow but long cylinders from MR images (see Eq. 1) [1]. Our previous studies of the complex sum method [1] required the knowledge of the object size. In this abstract, we present an improved approach that determines the effective magnetic moment without any *a priori* information.

Theory and Methods: An air cylinder in a gel phantom was previously imaged by a 3D gradient-echo sequence [1]. With the same imaging parameters and orientation, we simulated an air cylinder surrounded by water with $B_0 = 1.5T$, TE 5ms and 20ms [1-3]. The air cylinder was perpendicular to B_0 [1-3]. The radius of the air cylinder (a) was 0.8 mm and image resolutions (Δx and Δy) were 1 mm. The magnetic susceptibility difference between water and air was assumed to be -9.4 ppm in SI unit [4] so the effective magnetic moment is defined as $p = g a^2$ where g is defined as $0.5 \gamma B_0 \Delta \chi TE$, γ is the gyromagnetic ratio, $2\pi = 42.58$ MHz/T, and $\Delta \chi$ is the magnetic susceptibility between air and water. Therefore, p was -6.03 rad-mm² and -24.1 rad-mm² at TE 5ms and 20ms, respectively. The black dot shown in Fig. 1 at the center of the magnitude image represents the cross section of the cylinder. Eq.1 shows the overall complex MR signal S_i summed up within a circle of radius R_i (as any of the circles in Fig. 1). The overall complex MR signal happens to be a real number in the case of a cylindrical object. For this reason the center of the cylinder can be determined [1]. With three concentric circles shown in Fig. 1, re-arrangement of Eq.1 leads to Eq.2 in which p becomes the only unknown. Because the maximum phase value (θ_i) at the i -th circle outside the phase aliasing region is p/R_i^2 in Eq.2, if this maximum phase value is chosen to be less than 2.4 rad, then p can be uniquely determined. We also studied the uncertainty of p in the presence of both systematic (discretization) and thermal noise through error propagation (Eq.3) [2]. These two noise sources are uncorrelated. Eq. 3 tells us for what imaging parameters and R_i the uncertainty of p may be the least. Moreover, the phase profile from an image slice was similar to Fig. 2(b). With the proper choice of R_i , their corresponding phase values are listed in Table 1. We measured p from the air cylinder in the simulations and different slices of the gel images. The p values of the air cylinder in different slices at both TE 5 and 20ms are listed in Table 2. The uncertainties of p in columns 3 and 5 in Table 2 were estimated from Eq.3.

$$S_i = \pi \rho_0 p \int_{\rho/R_i}^{\rho/R_i} dx \frac{J_0(x)}{x^2} \quad (1) \quad (S_i - S_j) \times \int_{\rho/R_i}^{\rho/R_i} dx \frac{J_0(x)}{x^2} = (S_i - S_j) \times \int_{\rho/R_i}^{\rho/R_i} dx \frac{J_0(x)}{x^2} \quad (2)$$

$$\frac{\delta p}{p} = \sqrt{\frac{|h_1 - h_2|^2 \left[\frac{\Delta x \Delta y}{\pi SNR^2} (R_i^2 - R_j^2) + p^2 \epsilon_{ij}^2 (h_2 - h_1)^2 + |h_2 - h_1|^2 \left[\frac{\Delta x \Delta y}{\pi SNR^2} (R_i^2 - R_j^2) + p^2 \epsilon_{ij}^2 (h_1 - h_2)^2 \right] \right]}{|J_0(p/R_i R_i^2) (h_1 - h_2) + J_0(p/R_j R_j^2) (h_1 - h_2) + J_0(p/R_k R_k^2) (h_2 - h_1)|^2}} \quad (3)$$

Notations in equations: The effective magnetic moment p is defined as the above, ρ_0 and l are the spin density of water (including imaging parameters) and length of the cylinder, respectively. J_0 is the Bessel function. In Eq.3, ϵ_{ij} is the systematic noise (error) in each annual region, which can be estimated from Table 1.

TE = 5 ms	Phases (3, 2, 1)	Phases (2.4, 1.4, 1)
Systematic noise	0.3%	4.8%
Thermal noise only	2.6%	5.8%
TE = 20 ms	Phases (3, 2, 1)	Phases (2.4, 1.4, 1)
Systematic noise	0.4%	2.7%
Thermal noise only	1.3%	2.4%

Phase unit: rad, SNR=14.5 and tube radius=1 pixel

Table 2 Gel data analysis at TE 5 and 20 ms

Slice TE:ms	p_1 5ms	$\delta p_1/p_1$ (%)	p_2 20ms	$\delta p_2/p_2$ (%)	p_3 20ms	p_2 vs p_3 (%)
10	-6.93	6	-26.1	2	-27.7	6
19	-6.06	14	-23.7	9	-24.2	2
28	-5.96	13	-21.0	7	-23.8	12
37	-4.82	15	-18.3	9	-19.3	5
43	-4.27	6	-17.8	5	-17.1	4

p_i unit: rad-mm² $p_3 = p_1 \times 4$; $a = 0.8$ mm

Results: Most results show an uncertainty of p less than 10% [3]. For the uncertainty study in Table 1, the uncertainty of p decreases from $(\theta_1, \theta_2, \theta_3) = (2.4, 1.4, 1)$ to $(\theta_1, \theta_2, \theta_3) = (3, 2, 1)$ at two different TEs. At echo time, 20 ms, the uncertainty of p is less than that at the TE 5ms. These results are predicted by Eq.3. Eq. 3 implies that a longer echo time and a high signal noise ratio could lead to accurate p of the small cylinder. In Table 2, p_3 is calculated from p_1 and is the expected magnetic moment at TE 20ms. For the same slice of the gel phantom, p values at TE 5 and 20ms agree with each other within uncertainties (Table 2). As predicted by Eq. 3, in the same slice, the uncertainty of p at TE 20ms is also less than that at TE 5ms shown in Table 2.

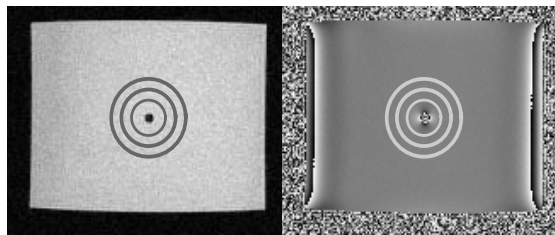


Fig.1(a) a magnitude image of a coronal slice (b) a phase image of a coronal slice from an air cylinder in a gel phantom with an in-plane resolution of 1x1 mm² and TE 20ms.

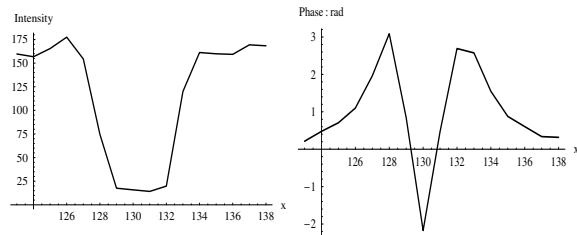


Fig. 2 (a) central magnitude profile in Fig. 1. (b) central phase profile in Fig. 1

Discussions and Conclusion: Results in Table 2 indicate that the air cylinder may slightly collapse at the bottom slice so its radius may be smaller. Simulations with a variety of cylinder radii support this conclusion. The simulations and experimental results well agree with each other. This outcome indicates a promising potential of this method.

References: [1] Cheng et al. M.R.I. 2007; p.1171-1180. [2] Hsieh et al. Medical Physics 2007; p. 2358. [3] Hsieh et al. Proc. ISMRM 2007; p. 2596. [4] Robson et al. AIChE journal 2005; p. 1633-1640