

# Autoregressive Moving Average (ARMA) Method for the Reconstruction of MR Images from Sparsely Sampled 3D k-Space

H. Peng<sup>1,2</sup>, M. R. Smith<sup>3</sup>, R. Frayne<sup>1,2</sup>

<sup>1</sup>Radiology and Clinical Neurosciences, University of Calgary, Calgary, Alberta, Canada, <sup>2</sup>Seaman Family MR Research Centre, Foothills Medical Centre, Calgary Health Region, Calgary, Alberta, Canada, <sup>3</sup>Electrical and Computer Engineering, University of Calgary, Calgary, Alberta, Canada

## Introduction

Magnetic resonance (MR) imaging usually reconstructs images from completely sampled but finite-sized  $k$ -spaces using the inverse Fourier transform (iFT)[1]. However, iFT on finite-size  $k$ -spaces introduces Gibbs ringing artifacts and degrades resolutions in the reconstructed images [2]. Moreover, real-time 3D MR imaging sometimes requires acquisition of a sparsely sampled  $k$ -space dataset [3]. For example, in continuously moving-table contrast-enhanced MR angiography sparse sampling is a necessity to ensure tracking of the contrast bolus. With sparse sampling, only a portion of the phase-encoded plane is sampled (with acquisition typically of the central region favored over the periphery). Autoregressive moving-average (ARMA) methods have been shown to extrapolate data beyond finite-sized  $k$ -space datasets [4], and may be of use when reconstructing sparsely sampled 3D  $k$ -space data. Our hypothesis is that ARMA methods have the ability to recover missing data and thus generate images with improved resolution and reduced artifact, compared to zero-filling algorithms (ZF; *c.f.*, Ref [5]).

## Theory

The ARMA method is a parametric approach that can be used to model (characterize) a finite-length data sequence. In signal processing terms, the measured  $k$ -space data are regarded as a subset of the transient response of an infinite impulse response (IIR) filter excited by excitation pulses. Data points,  $S_n$ , can be modeled and expressed as a linear combination of their previous values,  $S_{n-m}$  ( $1 \leq m \leq p$ ), and the excitation,  $e_{n-h}$  ( $1 \leq h \leq q$ ), *i.e.*,  $S_n = -\sum a_m S_{n-m} + \sum b_h e_{n-h}$ , where  $p$  and  $q$  are the autoregressive and moving-average filter orders, respectively. Of the algorithms used to successfully implement the ARMA method, the Transient Error Reconstruction Approach (TERA) is of particular interest [4]. We have extended the regular TERA algorithm (rTERA) into a new method where the image phase is used as a constraint, *i.e.*, constrained-phase TERA algorithm (CP-TERA). However, because it is not possible to obtain the true image phase  $\Phi_0(r)$ , image phase from the central zone of  $k$ -space  $\Phi_c(r)$  could be used as an estimate of the true phase:  $\Phi_0(r)$  contains mostly low spatial frequency components and thus  $\Phi_c(r)$  can be considered as a good representation of  $\Phi_0(r)$ . After parameters  $a_m$ ,  $b_h$  and  $e$  are determined from the measured MR data and the constraints, missing data would be recovered and the image function can be calculated explicitly.

## Method

Raw data from a quality-control phantom were acquired on a clinical 3 T scanner (Signa; General Electric Healthcare, Waukesha, WI). Hybrid  $k$ -space data ( $x$ - $k_y$ - $k_z$  with  $N_x = 256$ ,  $N_y = 256$  and  $N_z = 64$ ) were produced by taking the iFT of each readout (*i.e.*, in the  $x$ -direction) immediately after acquisition and then placing them into the appropriate location in the hybrid space. A series of simulated sparsely sampled  $k$ -spaces were generated (MATLAB, version 6.5.0, R13; Mathworks, Natick, MA) with constant central zone ratio  $\alpha$  (defined as  $\alpha = N_{\text{central}} / N_o$ , where  $N_{\text{central}}$  and  $N_o$  are the number of pixels in the central zone and in the full phase-encoded plane, respectively) and varying the sparsely sampled density  $\beta$  (defined as  $\beta = N_{\text{acq}} / (N_o - N_{\text{central}})$ , where  $N_{\text{acq}}$  is the number of points in peripheral region). Images were reconstructed from the fully sampled hybrid  $k$ -space (*i.e.*, the true image  $I_0$ ) and from simulated sparsely sampled  $k$ -spaces using (a) ZF ( $I_{\text{ZF}}$ ), (b) rTERA ( $I_{\text{rTERA}}$ ) and (c) CP-TERA ( $I_{\text{CP-TERA}}$ ). The ZF method replaces the missing  $k$ -space data with zeros. The quality of the resulting images was assessed by visual inspection and quantified by calculation of performance error (PE) defined as  $\text{PE} = \sqrt{\sum (\zeta_i - o_i)^2} / \sqrt{\sum o_i^2}$  where  $\zeta_i$  and  $o_i$  denote pixels from  $I_{\text{TERA}}$  (or  $I_{\text{ZF}}$ ) and  $I_0$ , respectively. The PE summation was performed over all pixels in the image (global performance error, GPE) and over all  $3 \times 3$  kernels in a small high-frequency region (local performance error, LPE).

## Results

Both TERA approaches produced images that were qualitatively and quantitatively superior to those obtained by ZF. CP-TERA was better able to recover the missing  $k$ -space data points than rTERA (Figs 1d vs 1c). Hence, CP-TERA (Fig 1h) showed better image reconstruction performance than both ZF (Fig 1f) and rTERA (Fig 1g). Global and local PE (GPE, LPE) for CP-TERA images (Fig 2) were smaller than those when using ZF and rTERA, indicating superior image reconstruction performance with sparsely sampled  $k$ -space by our proposed algorithm.

## Discussion

Compared with the more simple and commonly used ZF reconstruction and with the rTERA, CP-TERA is a better technique to reconstruct images from sparsely sampled  $k$ -space, as it results in good image quality and reduced global and local PE. This is an interesting finding demonstrating that TERA successfully interpolates the missing data. Optimization of CP-TERA to achieve computational efficiency is our next step.

**References** [1] Kumar, *et al. JMRI* 1975; **18**: 69-83. [2] Wood, *et al. MRM* 1985; **2**: 517-526. [3] Sabati, *et al. PMB* 2003; **48**: 2739-2752. [4] Smith, *et al. MRM* 1986; **4**: 257-261. [5] Bernstein, *et al. JMRI* 2001; **14**: 270-280.

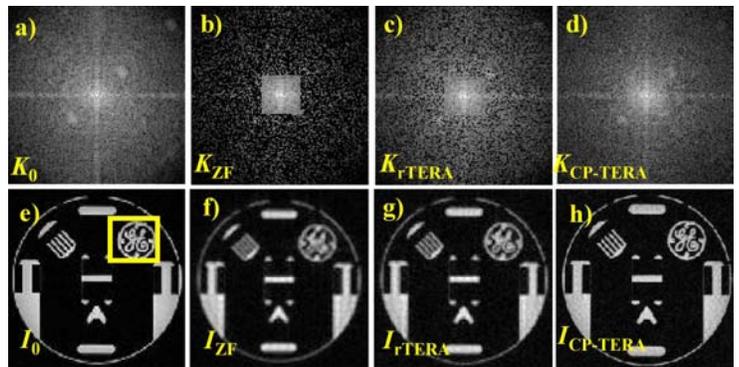


Fig 1: 2D representation of 3D  $k$ -space datasets and the corresponding reconstructed images. (a) Completely sampled  $k$ -space and (e) the reference image; (b) Sparsely sampled  $k$ -space with  $\alpha = 6.25\%$  and  $\beta = 30$ , and (f) ZF image, (c) partially recovered  $k$ -space and (g) the corresponding image by rTERA and (d) partially recovered  $k$ -space and (h) the corresponding image by CP-TERA. Yellow outlined region in (e) used for local performance error calculation.

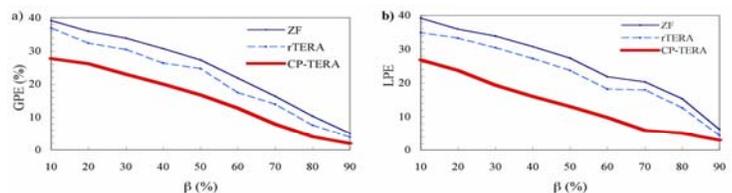


Fig 2: Global (a) and local (b) performance error (PE) versus  $\beta$  (using  $\alpha = 6.25\%$ ) for ZF, rTERA and CP-TERA images. Local PE is defined over the yellow region shown in Fig 1e in order to highlight ability to reproduce high-frequency structures.