

# Effect of Background Velocity Error on Measured Time of End-systole in Patients with Aortic Regurgitation by Phase Contrast MRI

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**Background:** To quantify the severity of aortic valvular regurgitation, the regurgitant volume  $V_{\text{reg}}$  or regurgitant fraction RF, where  $\text{RF} = V_{\text{reg}} / V_{\text{for}}$ , with  $V_{\text{for}}$  the forward stroke volume, is often measured. Phase-contrast MRI (PC-MRI) is frequently used for this purpose. However, PC-MRI is well known to suffer from stationary offsets due to nonzero background velocity  $v_{\text{BG}}$ . Methods to correct for  $v_{\text{BG}}$  have been developed but are not perfect. It is therefore impossible to know the true deviation of the measured velocity from the actual flow velocity. The magnitude of  $v_{\text{BG}}$  is dependent on several factors, including the scan plane and spatial position; they may arise from a variety of effects, including eddy currents and concomitant gradients. The errors  $v_{\text{BG}}$  are commonly at least  $\pm 2$  cm/s in magnitude (Lloyd, 2005). Even a small error  $v_{\text{BG}}$  of the order of  $\pm 1$  to 2 cm/s has a large impact on the calculation of  $V_{\text{reg}}$  or RF (Gatehouse, 2005). It will also affect the interpolated time the measured velocity crosses the zero line, corresponding to the end of systole  $T_s$ . An accurate measurement of  $T_s$  is critical, as this determines the beginning time for the diastolic integration of velocities that leads to the calculation of  $V_{\text{reg}}$ . The impact of the velocity error offset  $v_{\text{BG}}$  on  $T_s$ , and hence on its contribution to errors in the measurement of  $V_{\text{reg}}$  or RF, has not been investigated. Therefore, we performed a theoretical error analysis of the impact of  $v_{\text{BG}}$  on  $T_s$ .

**Methods and calculations:** Phase contrast flow data in aortic regurgitation data can be approximated as a quadratic function in time near the minimum (which occurs in early diastole, shortly after the curve crosses the zero velocity value at  $t_0$ , taken as the graphically determined  $T_s$ ); this is written as

$$v(t) = a(t - t_{\min})^2 - |v_{\min}| \quad (1)$$

Introducing an offset error velocity, (1) becomes

$$v(t) = a(t - t_{\min})^2 - |v_{\min}| \pm v_{\text{BG}} \quad (2)$$

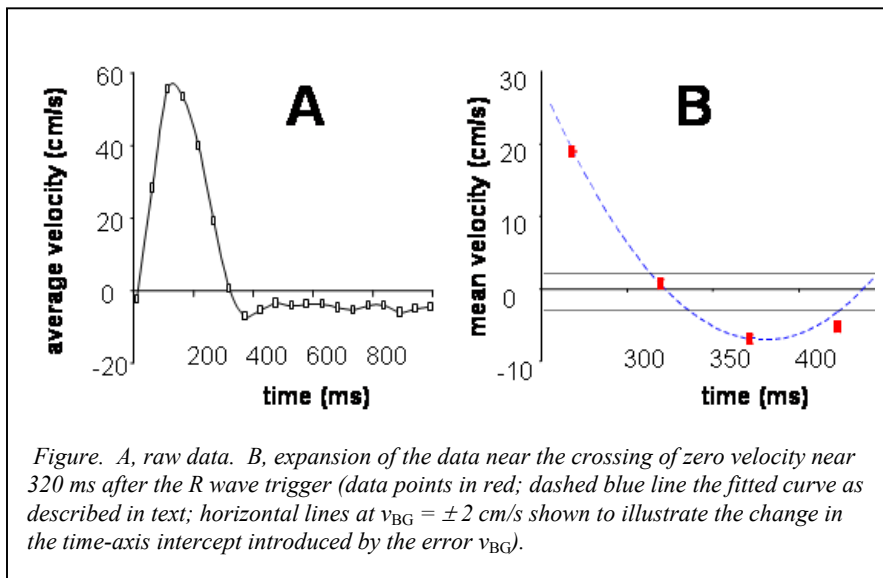
Setting equation (2) equal to zero and solving for its roots yields the error contributed by the introduction of the unknown  $v_{\text{BG}}$  on the experimentally determined  $T_s$ . The “left” or lesser root is the meaningful value, resulting in

$$t_{\text{r}} = t_{\min} - \left[ \frac{|v_{\min}| \pm v_{\text{BG}}}{a} \right]^{1/2} \quad (3)$$

And this is the total error in the measurement of  $T_s$  due to the contribution of  $v_{\text{BG}}$ .

**Results:** As an example, the mean flow velocity as measured by phase contrast MRI in the proximal ascending aorta in a typical patient with moderate aortic regurgitation is shown in the Figure, using ECG gating triggered on the R wave. A curve fit based on equation (1) was performed to the velocity data. Fit values were  $a = 2.1 \times 10^{-3} \text{ cm/s}^3$ ,  $t_{\min} = 380 \text{ ms}$ , and  $|v_{\min}| = 7.1 \text{ cm/s}$  in this case; the fit is shown in the dashed line in panel B. The raw data yield  $T_s = 323 \text{ ms}$  after onset of the R wave trigger; incorporating the effect of an arbitrarily chosen  $v_{\text{BG}}$  of  $\pm 2 \text{ cm/s}$  (for illustration purposes),  $T_s$  is found to range between 315 and 331 ms. This small range is smaller than the cine frame duration (typically 30 to 40 ms in PC-MRI scans).

**Conclusions:** Small offset errors occur in PC-MRI measurement of velocity. However, though this error may have a large effect on  $V_{\text{reg}}$  and RF, it has little impact  $T_s$  and need not be considered during its measurement.



## References:

- (1) Lloyd SG, et al. (2005) Proc Intl Soc Mag Reson Med. 3:1729.
- (2) Gatehouse PD, et al. (2005). Eur Radiol. 15 :2172-2184.