

Diffusion weighted imaging with a hole-burning sequence

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Introduction

We describe a method of acquiring diffusion weighted images that is based on a hole burning technique [1-2] instead of using the common bipolar gradients. The stripes burned into the magnetization are on subvoxel level, so that they are not resolved in the image. A b-value can be defined analogously to conventional diffusion experiments which does not exclusively depend on the parameters of the sequence, but also on the diffusion and the T_1 value. Because only the longitudinal magnetization is affected, the results are independent of T_2 -effects.

Methods

The sequence used is made up of a pre-experiment that creates a diffusion and T_1 -weighted z-magnetization which is read out with a subsequent snapshot-FLASH-experiment [3] (fig. 1). The pre-experiment is essentially composed of $N = 25$ short hard pulses (duration $\tau = 3 \mu\text{s}$, pulse separation $\Delta = 1 \text{ ms}$) applied under a gradient $G = 0.45 \text{ T/m}$. This pulse train burns a "hole-comb" with a spatial distance of $\Delta x = 2\pi / (\gamma G \Delta) = 52 \mu\text{m}$ into the longitudinal magnetization (hole width approx. $5 \mu\text{m}$), each stripe modulated with a sinc-shaped function: $\text{sinc}(N/2 \Delta \gamma G x)$. The maxima are also modulated with a sinc-shaped function with the form $\text{sinc}(N/2 \Delta \gamma G x)$. After each pulse train, the generated transversal magnetization is spoiled. The system is allowed to evolve for a time $T_{ev} = 25 \text{ ms}$. During this time, the longitudinal magnetization is rebuilt due to T_1 relaxation; in addition, the burned profile is blurred due to diffusion (z-magnetization is conserved). After the time T_{ev} , the entire procedure is repeated L times, with the hole-comb remaining at its original position. A steady state is achieved after $L \approx 20$ loops (fig. 2); this steady state depends on the diffusion coefficient and on T_1 and is read out with a FLASH-experiment ($TE = 2.5 \text{ ms}$, $TR = 4.3 \text{ ms}$, centric reordered). NMR imaging was performed on a Bruker AMX-500 system at 11.75 T with a spatial resolution of $156 \mu\text{m}$ in-plane (three stripes per pixel). For simulations, it is sufficient to model the longitudinal magnetization of a repeated unit cell with periodic boundary conditions, only taking the influence of T_1 , the diffusion, and the applied pulses into account [4].

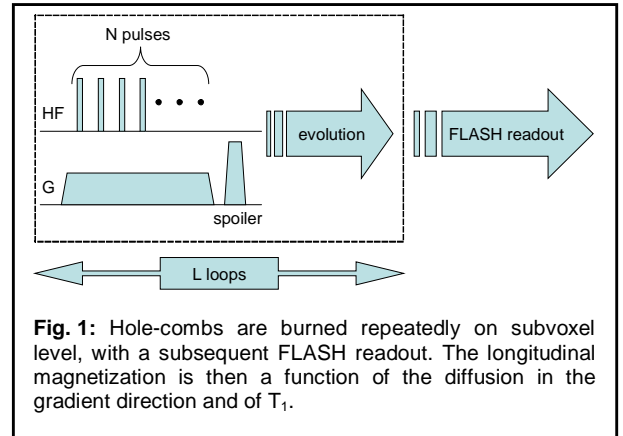


Fig. 1: Hole-combs are burned repeatedly on subvoxel level, with a subsequent FLASH readout. The longitudinal magnetization is then a function of the diffusion in the gradient direction and of T_1 .

Results

Experiments were performed on a phantom filled with three different relevant solutions: normal water, doped water (with Gadolinium), and oil. The first two solutions have equal diffusion coefficients and different T_1 values, whereas the last two have equal T_1 values but different diffusion coefficients, thereby showing both diffusion (fig. 2) and T_1 -weighting (fig. 3). The acquired signal progression corresponds well to the simulations. In fig. 4 images are shown for different values of the loop counter L . One can see the signal loss due to the saturation of spins diffusing into the hole-comb. The b-value is dependent not only on the sequence parameters, but also on the diffusion coefficient and T_1 (in case that it is defined as usual as $b = 1/D \ln(M_0/M)$). Here we obtain $b = 932 \text{ s/mm}^2$ for normal water, $b = 324 \text{ s/mm}^2$ for doped water, and $b = 5693 \text{ s/mm}^2$ for oil.

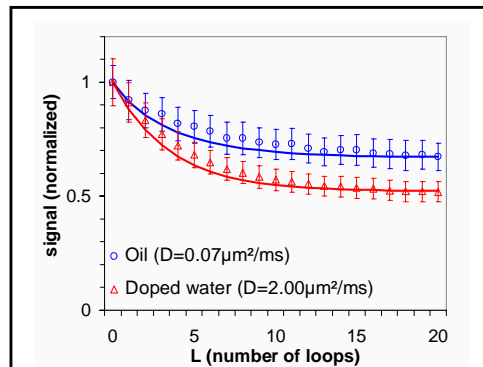


Fig. 2: Diffusion weighting depending on the number of loops L . Two compartments with equal $T_1 = 360 \text{ ms}$ but unequal diffusion coefficient are shown (experiment and simulations).

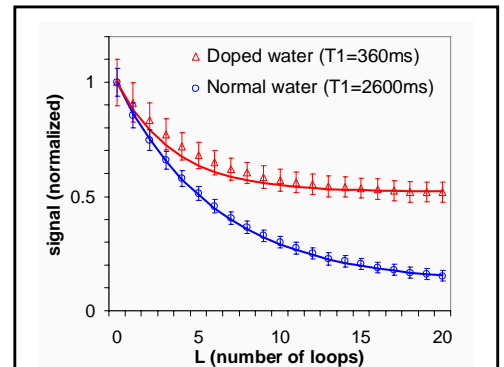


Fig. 3: Diffusion weighting depending on the number of loops L . Two compartments with equal $D = 2.00 \mu\text{m}^2/\text{ms}$ but unequal T_1 values are shown (experiment and simulations).

Discussion & Conclusion

We have shown that the presented sequence is able to acquire diffusion weighted images without T_2 -effects with a diffusion weighting (b-value) dependent on diffusion itself and on T_1 , which may in certain cases provide a good contrast. Furthermore, it is relatively easy to simulate the sequence in order to make predictions and optimize parameters. After further calculations, it might be possible to quantify the T_1 and diffusion coefficient, as well as use these diffusion coefficients to measure diffusion tensors by varying the gradient strength and direction.

Acknowledgement

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Reference

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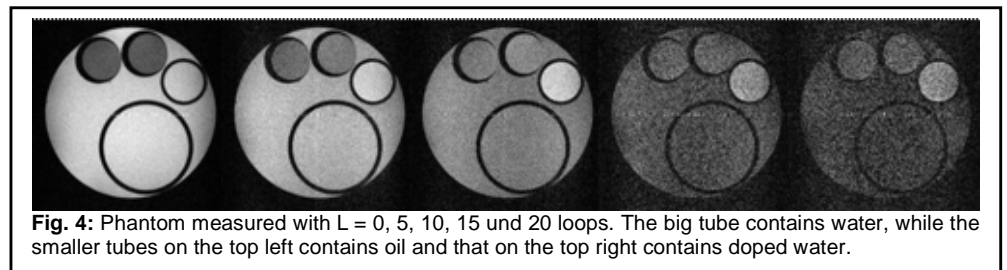


Fig. 4: Phantom measured with $L = 0, 5, 10, 15$ und 20 loops. The big tube contains water, while the smaller tubes on the top left contains oil and that on the top right contains doped water.